



Klas Bengtsson, October 2013

# Integrated Vision

# Introduction



There are endless applications in which a Vision Guided Robot can add flexibility, reduce hard automation cost at the same time meeting high quality standards and safety guide lines. The only question is if it can be done in a cost effective and reliable way?

ABB Integrated Vision does not compromise anything. The most advanced vision tools needed are now an integral part of ABB robots and with minimum experience or programming time perform a variety of applications that work 24-7.

# Introduction

## ABB Smart Camera

**Compatible to Cognex  
In-sight series**

**Integrated  
Lightning**

**75x55x47  
mm**

**IP 67**



**4 different lenses**

**Autofocus optics**

**Ethernet, power  
and I/O  
via industrial  
M12 connectors**

**800x600 or 1280x1024  
resolution**

# Targeted Applications

## Find It, Check It, Trace It



***Find it***



***Check it***



***Trace it***

# Targeted Applications

## Find It

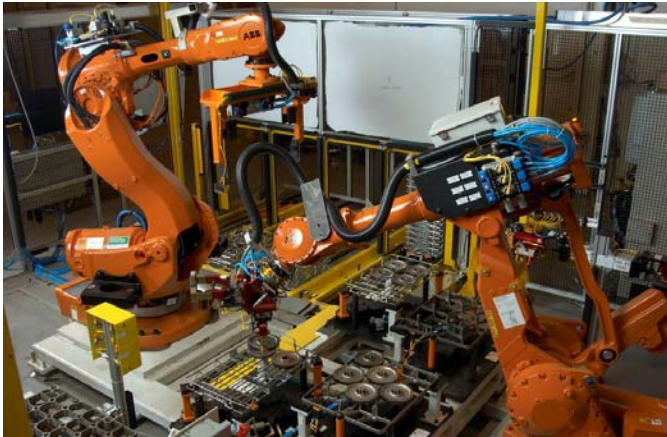


- Vision guided robots find items without costly hardware arrangements

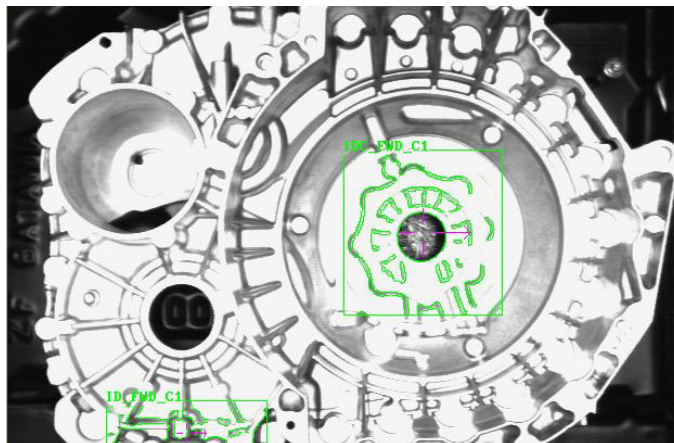


# Targeted Applications

## Check It



- Inspection of parts before passing on to next production step
  - Classification of defect types
  - Tools for measuring surface defects
- Verify tolerances



# Targeted Applications

## Trace It



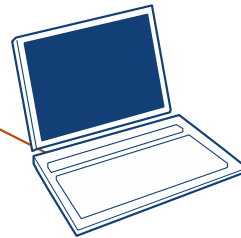
- Reading and verification of 1D/2D barcodes
- Text reading and verification
- OCR/OCV reading

# How It Works

## Hardware Setup

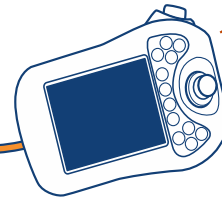
### PC

Used for setup and programming via RobotStudio. Can be removed during production



### FlexPendant

Monitoring and simple maintenance



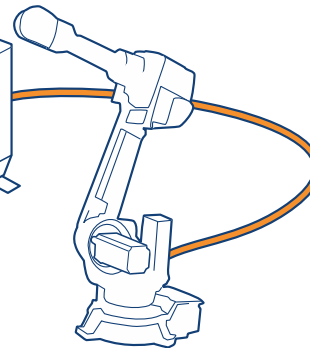
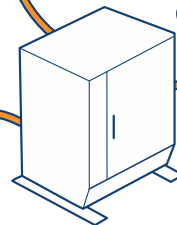
### ABB Smart Camera

Smart camera with embedded image processing  
Cognex In-sight compatible



### IRC5

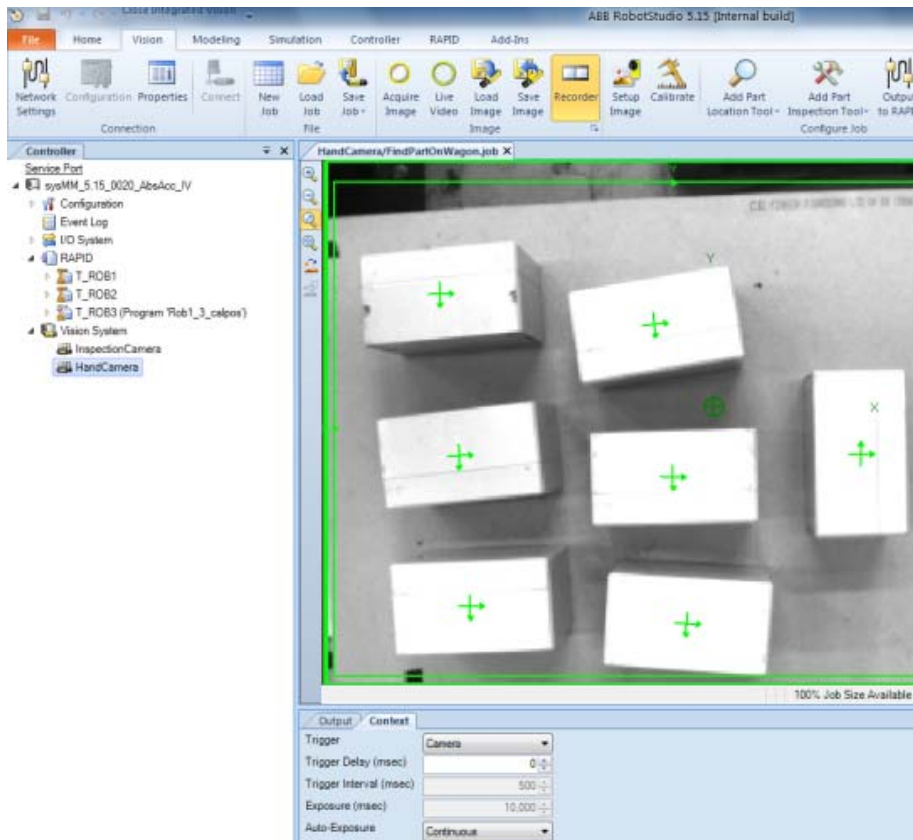
Camera discovery, standard  
Rapid instructions, communication runtime including result queues.





# How It Works

## Programmed in RobotStudio



- Both robot and camera are programmed in RobotStudio
- Camera an integral part of the system
- Easy to understand “How To” programming tabs in RobotStudio
- Program sent to controller via Ethernet but is NOT needed in runtime

# How It Works

## > 50 Task Oriented Vision Tools

### Location Tools

#### Compute Fixture

Calculates a Fixture location based on mathematical expressions; reports the X,Y coordinates and angle of the mathematically computed Fixture. Outputs a Tool Fixture that can be referenced by o...



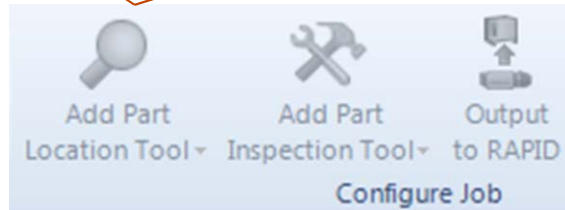
#### Color Blobs (1-10)

Locates up to 10 groups of connected color pixels, called blobs; reports the X,Y coordinates of the centroid of the found blobs. Outputs a Tool Image and Tool Fixture that can be referenced by other to...



#### Blobs (1-10)

Locates up to 10 groups of dark or light-colored connected pixels, called blobs; reports the X,Y coordinates of the centroid of the found blobs. Commonly used as a Fixture to orient other vision tools...



- Select from > 50 task oriented vision tools from a list
- Comprehensive description of "How To Use" pop up when a tool is chosen

# How it works

## Simple Rapid Programming

```
12  PROC Run()  
13      VAR CameraTarget camTgt;  
14  
15      !Load the camera job  
16      CamLoadJob myCamera, "FindTheBox.job" \Flush;  
17      CamStartJob myCamera;  
18  
19      !Move to the photo position (if the camera is handheld)  
20      MoveL pPhoto, v1000, fine, tool0 \Wobj:=wobjCamera;  
21  
22      !Take photo and get result  
23      CamReqImage myCamera;  
24      CamGetResult myCamera, camtgt;  
25  
26      !Approach vision target  
27      wobjCamera.oframe := camtgt.cframe;  
28      MoveL pPickTarget, v100, fine, tool0 \Wobj:=wobjCamera;  
29  ENDPROC
```

- Basic camera commands written in RAPID are available in a Library
- Complete tasks ready to be used in Snippets



# Key Values

## Scalability



- No need for a PC or a special CPU inside robot controller to run the vision cameras
- Each camera has its own CPU so there is enough capacity to handle whatever number of cameras - scalable

**No need to worry about  
PC requirements**

# Key Values

## Auto Focus



- The built in Auto-focus simplifies the use in cells where parts with different heights are handled
- Ideal in areas where the camera is hard to reach



# Key Values

## Built in Lighting



- The built-in lights
  - Provides basic front lighting for standard applications
- Allows user to start using the camera without a separate lighting system

# Key Values

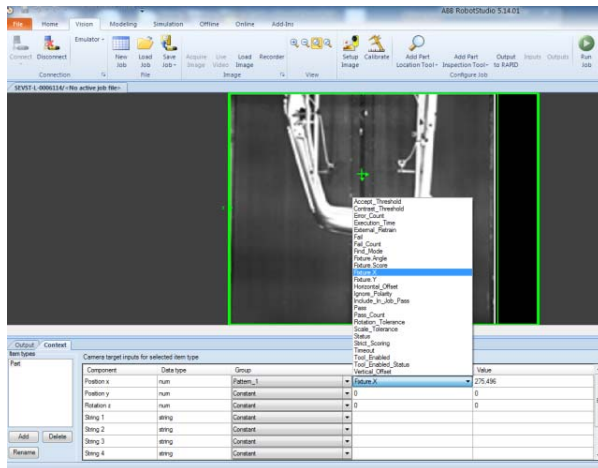
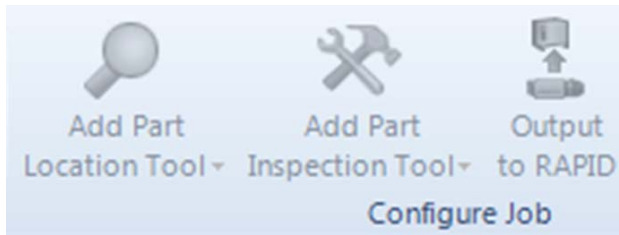
## In-Sight Compatible



- Any Cognex In-Sight camera automatically plugs into the ABB Integrated Vision system
- 6 different color cameras
- Up to 2448x2048 resolution
- IP68 Stainless steel
- 43 different models

# Key Values

## Simplicity of Installation, Calibration and Programming



**Integrated generic  
vision  
tool for all purpose  
applications**

- Minimum installation time
  - Pre-configured and simple to calibrate
- One-stop-shop
  - Smart camera, power and cables, SW
- Cuts programming time
  - Vision and programming in one common tool (RobotStudio)

# Key Values

## Cutting Edge Vision Technology

- The ABB Integrated Vision, powered by the Cognex, is a state-of-the-art vision system designed to work on the manufacturing floor under the most challenging of conditions
- The vision system is intuitive and easy to work with, automatically selects features and proposes parameters, minimizing deployment
- The result is very reliable even in the most challenging vision application

# Key Values

## Small, Rugged and Precise



- 75 x 55 x47 mm small, the ABB Integrated Vision camera is easy to squeeze in wherever it is needed
- The housing withstands caustic environments and has an IP 67 protection to work in tough environments
- High resolution 1280X1024
- Medium resolution 800X600



# Key Customer Values Summary



**Time saving**



**Intuitive**



**Reliable**

More Vision Guided Robotics applications can be deployed faster by more people and with greater reliability using ABB Integrated Vision

Power and productivity  
for a better world™

